Bi-Objective Lexicographic Optimization in Markov Decision Processes with Related Objectives

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slips to different direction with some probability



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Slips to different direction with some probability
Cannot move through a



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cannot move through a



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- Image: Second state of the second state of



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• Maximize
$$\mathbb{P}(\textcircled{\baselinetwidth} \rightsquigarrow \textcircled{\baselinetwidth})$$



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Reach I as fast as possible

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► Path : 😔

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Reward: 0



▶ Path : $\bigcirc \xrightarrow{c} \bigcirc$

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Reward: 2





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Reward: 3

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• Mean-payoff (MP): Average reward at limit : $\rho \mapsto \lim_{n\to\infty} \frac{1}{n} \text{Reward}(\rho_n)$



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 \blacktriangleright Strategy : Paths \rightarrow Actions

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$$\{ \fbox{-} \mapsto c, \textcircled{i} \mapsto a, \textcircled{i} \mapsto a \}$$



 $\blacktriangleright Strategy : Paths \rightarrow Actions$

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Fixing a strategy creates a Markov chain

Find a strategy σ that optimizes



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• expected mean payoff $\mathbb{E}_{\sigma}(\mathsf{MP})$



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Lexicographic multi-objective :

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 - Optimize objective 1

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- Lexicographic multi-objective :
 - Optimize objective 1
 - Optimize objective 2 among strategies optimizing objective 1

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Problem statement

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Reach the target as soon as possible

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 - Among $\sigma \in \Sigma_{\Diamond T}$, expected conditional distance to target is minimum

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 $len_T: \rho \mapsto length of the shortest prefix of <math>\rho$ reaching T

Find a strategy that

- maximizes the probability to reach the target,
- minimizes the conditional expected length to the target

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$$\mathsf{Val}(s) \neq \sum_{s'} \mathsf{P}(s, a, s') \cdot \mathsf{Val}(s')$$

Remove bad states s such that Val(s) = 0



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Find the strategy arg min_{σ'} $\mathbb{E}_{\sigma'}(\text{len}_{r})$ in M'

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Change the probability measure by redistributing probabilities.

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Probability in M'

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Remove some suboptimal strategies

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Remove some suboptimal strategies such that optimizing objective 2 in M' automatically optimizes objective 1 in M.

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$$\sigma \notin \operatorname*{arg\,max}_{\sigma'} \mathbb{P}^{M}_{\sigma'}(s_{0} \models \Diamond \textcircled{i})$$
$$\Downarrow$$
$$\mathbb{E}^{M'}_{\sigma}(\operatorname{len}_{\textcircled{i}}) = \infty$$

Experimental results

layouts	$\mathbb{P}(\textcircled{} \rightsquigarrow)$	min(: 🕮 ↔ 🆤)	$\mathbb{E}_{opt}(\rightsquigarrow \heartsuit)$	$\mathbb{E}_{storm}(\rightsquigarrow)$
1	0.66	9	76.48	76.48
2	0.52	18	299.75	629.16
3	1.00	2	2.40	12.12
4	1.00	3	3.44	34.47
5	1.00	6	7.71	137.56
6	0.68	10	264.04	9598.81
7	1.00	5	112.69	9367.02
8	0.91	10	11.49	5879.63
9	1.00	3	3.66	5711.76
10	0.91	5	12.89	149357.57

Table: Comparison of expected conditional distance to the target given by the strategy optimizing distance and the strategy given by model checker $\rm Storm$

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General problem

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We gave a prunning-based algorithm where:

f	g
reachability	distance/cost to target
safety	mean payoff
safety	any measurable function

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Thank You!

